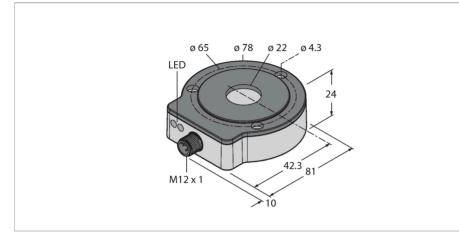


RI360P0-EQR24M0-INCRX2-H1181 Contactless Encoder with Stainless Steel Housing – Incremental: 1 ... 5000 ppr Premium Line

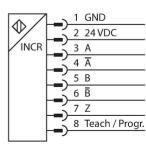




Features

- Active face, plastic PA12-GF30
- Housing, stainless steel V4A (1.4404)
- Status displayed via LED
- Immune to electromagnetic interference
- 1024 pulses per revolution (default)
- 360, 512, 1000, 1024, 2048, 2500, 3600, 4096, parametr. via Easy-Teach
- Free parametrization of the pulse number in the range from 1 to 5000 via PACTware™
- Position of z-track set via Easy-Teach
 Burst function, absolute angular position output incrementally per Easy-Teach pulse
- 10...30 VDC
- Male M12 x 1, 8-pin
- Push-pull A, B, Z, A (inverse), B (inverse)

Wiring diagram



Technical data

| Туре | RI360P0-EQR24M0-INCRX2-H1181 |
|---|--|
| ID | 1590912 |
| Measuring principle | Inductive |
| General data | |
| Max. Rotational Speed | 10000 rpm |
| | Determined with standardized construction, with a steel shaft Ø 20 mm, L = 50 mm and reducer Ø 20 mm |
| Starting torque shaft load (radial / axial) | not applicable, because of contactless measuring principle |
| Nominal distance | 1.5 mm |
| Repeat accuracy | ≤ 0.01 % of full scale |
| Linearity deviation | ≤ 0.05 % f.s. |
| Temperature drift | ≤ ± 0.003 % / K |
| Output type | Incremental |
| Resolution, incremental | 1024 ppr |
| Electrical data | |
| Operating voltage | 1030 VDC |
| Residual ripple | ≤ 10 % U _{ss} |
| Isolation test voltage | ≤ 0.5 kV |
| Short-circuit protection | yes / Cyclic |
| Wire breakage/Reverse polarity protection | yes / yes (voltage supply) |



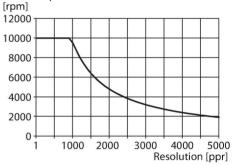
Technical data

| Pulse frequency max. | 200 kHz | |
|---|---|--|
| Signal level high | min. $U_{\scriptscriptstyle B}$ - 2 V | |
| Signal level low | max. 2.0 V | |
| Output function | 8-pin, Push-Pull/HTL | |
| Sample rate | 1000 Hz | |
| Current consumption | < 100 mA | |
| Mechanical data | | |
| Design | EQR24 | |
| Dimensions | 81 x 78 x 24 mm | |
| Flange type | Flange without mounting element | |
| Shaft Type | Hollow shaft | |
| Shaft diameter D [mm] | 6 6.35 9.525 10 12 12.7 14 15.875 19.05 20 | |
| Housing material | Stainless-steel/Plastic, 1.4404 (AISI 316L)/ PA12-GF30 | |
| Electrical connection | Connector, M12 × 1 | |
| Environmental conditions | | |
| Ambient temperature | -25+85 °C | |
| | Acc. to UL approval to +70 °C | |
| Vibration resistance | 55 Hz (1 mm) | |
| Vibration resistance (EN 60068-2-6) | 20 g; 103000 Hz; 50 cycles; 3 axes | |
| Shock resistance (EN 60068-2-27) | 100 g; 11 ms ½ sine; 3 × each; 3 axes | |
| Continuous shock resistance (EN 60068-2-29) | 40 g; 6 ms ½ sine; 4000 × each; 3 axes | |
| | IP68 | |
| Protection class | IP69K | |
| Protection class MTTF | | |
| | IP69K 138 years acc. to SN 29500 (Ed. 99) 40 | |
| MTTF | IP69K 138 years acc. to SN 29500 (Ed. 99) 40 °C | |



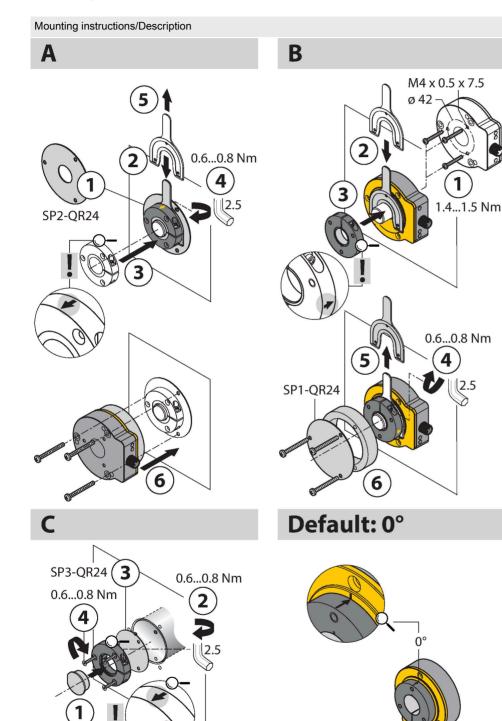
Functional principle

The measuring principle of inductive angle sensors is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields. Rotation speed





Mounting instructions



Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the sensor operates absolutely wear-free and is immune to magnetized metal splinters and other interference fields. Wrong installation is hardly possible.

The adjacent figure shows the two separate units, sensor and positioning element. Mounting option A:

First, interconnect positioning element and rotatable shaft. Then place the encoder above the rotating part in such a way that you get a tight and protected unit.

Mounting option B: Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

Mounting option C:

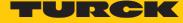
If the positioning element is to be screwed on a rotating machine part and not on a shaft, install first the dummy plug RA8-QR24. Then tie up the bracket. Screw on the encoder via the three bores.

The separately arranged sensor and positioning element inhibit that compensating currents or damaging mechanical loads are transmitted via the shaft to the sensor. In addition, the encoder remains tight and highly protected during its entire lifespan.

The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status. Optionally, you can use the shields which are included in the accessories to increase the allowed distance between positioning element and sensor.

Status display via LED green steady: Sensor is operative yellow steady: Positioning element has reached the end of the measuring range. This is indicated by a weaker signal. yellow flashing: Positioning element is outside the measuring range. off: Positioning element is in the measuring range

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Individual Parameterization (Teaching with Positioning Element)

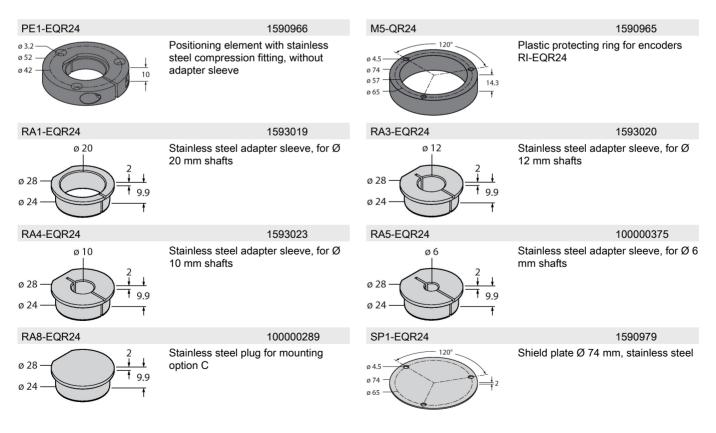
| Jumper between teach | Gnd Pin 1 | Ub Pin 2 | LED |
|----------------------|--------------------|-------------------------------|-------------------------|
| input Pin 8 | | | |
| 2 s | Z-track zero point | One-time triggering of burst | Status LED flashes then |
| | teaching | function | turns steady after 2 s |
| 10 s | CCW rotation | CW rotation direction | After 10 s status LED |
| | direction | | flashes fast for 2 s |
| 15 s | - | Factory setting (z-track, CW) | After 15 s power and |
| | | | status LED alternate |

To avoid unintended teaching, keep pin 8 potential-free.

| Preset Programming Mode (Teaching without Positioning Element) | | | | | |
|--|----------------------|----------------------|----------------------------------|--|--|
| Jumper between teach | Gnd Pin 1 | Ub Pin 2 | LED | | |
| input Pin 8 | | | | | |
| | 2 s | 2 s | Status LED steady, flashes after | | |
| | Resolution setting | Resolution setting | 2 s as long as selection mode is | | |
| | mode active for 10 s | mode active for 10 s | active | | |
| 360 pulses/360° | Start value | | 1 x flashing | | |
| 512 pulses/360° | Press once | | 2 x flashing | | |
| 1000 pulses/360° | Press twice | | 3 x flashing | | |
| 1024 pulses/360° | Press three times | | 4 x flashing | | |
| 2048 pulses/360° | Press four times | | 5 x flashing | | |
| 2500 pulses/360° | | Start value | 1 x flashing | | |
| 3600 pulses/360° | | Press once | 2 x flashing | | |
| 4096 pulses/360° | | Press twice | 3 x flashing | | |
| 5000 pulses/360° | | Press three times | 4 x flashing | | |

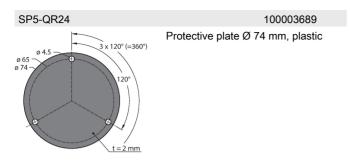
To avoid unintended teaching, keep pin 8 potential-free.

Accessories

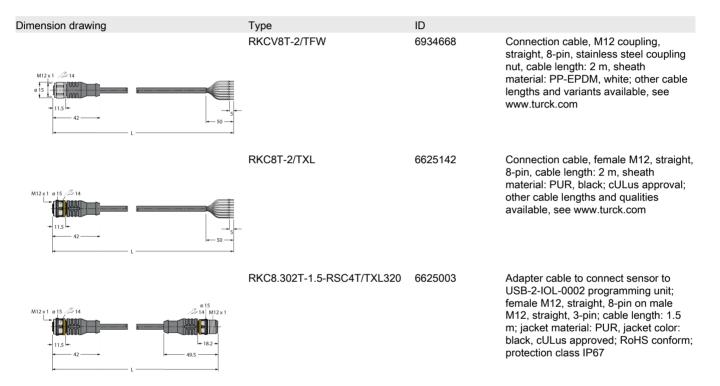


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Wiring accessories



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