Selection Guide

Safety and Reliability -Monitoring and Indication LS-Titan® position Switches

LS-Titan® position switch LSE-Titan® position switch





Quick and Flexible

Metal or plastic versions

The LS-Titan position switches are optionally available in robust metal enclosures or in light insulated enclosures. Exchangeable metal or plastic operating heads make the LS-Titan position switch particularly flexible.

Modular design, vibration proof and maintenance-free Cage-Clamp terminations guarantee extremely fast installation.

Electronic position switch with programmable operating point

The highlight is the world's first electronic position switch, the LSE-Titan. Its freely programmable operating point can be set individually at any time:

Move to the operating point – press the Set key – ready!

The LSE conforms to safety category 3 with EN 954-1 of the machine guideline just as the electromechanical position switches. The devices are thus suitable for use with safety applications designed to protect persons or processes.

LS-Titan® Pos UL/CSA 4X, 13 IP 66	ition Sw	itch		Contact sequence diagram for plunger and roller plunger	Plunger EN 50 047	Roller plunger EN 50 047	Contact sequence diagram for spring rod
	positively o	function with pening con- /EN 60947-5-1		Contact sequence contact ■ closed □ open Zw = Positive opening clearance			
plastic version		2B⊖	0	0 3.0 6.1 11-12 NC 21-22 NC	LS-02		
	1M	1B ⊝	O- 13 L 21 14 22	0 4.3 6.1 13-14 NO 21-22 NC 3.0 Zw = 4.5 mm	LS-11	LS-11/P	
9	1M	1B ⊝	O-\(\frac{17}{18}\)\frac{125}{26}	0 3.0 6.1 25-26 NC 17-18 NO 2.1 2w = 4.5 mm	LS-11D		
	1M	1B⊝	0	0 3.0 6.1 21-22 13-14 21-22 13-14 2.52 13-14 2.52 13-14 2.52	LS-11S*	LS-11S/P	0' 13' 26' 21-22 13-14 21-22 13-14
	2M	_	0	0 4.3 6.1 13-14 N0 23-24 N0	LS-20		
metall version	_	2B⊝	0	0 3.0 6.1 11-12 NC 21-22 NC	LSM-02		
_	1M	1B⊝	O- 13 L 21 14 22	0 4.3 6.1 13-14 NO 21-22 NC 3.0 Zw = 4.5 mm	LSM-11	LSM-11/P	
10	1M	1B⊝	0-\frac{17}{18}\frac{1}{26}	0 3.0 6.1 25-26 NC 17-18 NO 2.1 Zw = 4.5 mm	LSM-11D		
	1M	1B⊝	0	0 3.0 6.1 21-22 13-14 21-22 13-14 1.5 2w = 4.5 mm	LSM-11S*	LSM-11S/P	0' 13' 26' 21-22 13-14 21-22 13-14 21-22 13-14 21-27 2w = 19'
	2M	_	0	0 43 6.1 13-14 23-24 N0 2.1	LSM-20		

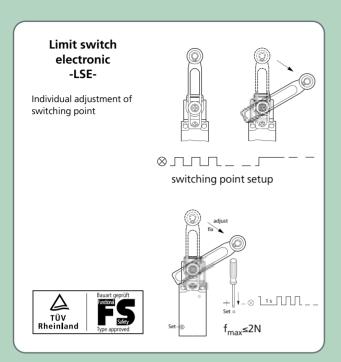
LSE-Titan® electronic position switch Setting a variable operating point

The LSE electronic position switch has an operating point that can be set variably. Two fast and bounce-free PNP switch outputs enable high switching frequencies. They are protected against short-circuit and overload and are equipped with an abrupt switching behaviour. This guarantees a defined and reproducible operating point. The actual operation point is in a range between 0.5 mm to 5.5 mm (supplied ex-works = 3 mm).

The setting to the "new" operating point is performed as follows: The plunger must be moved from the "old" to the "new" operating position. Now the set button should be pressed for a duration of 1 sec. The LED now flashes with a higher pulse frequency and the new operation point is set retentively.



Spring-Rod	Contact sequence diagram for roller	Roller lever EN 50 047	Contact sequence diagram for rotary	Rotary lever EN 50 047	Adjustable roller lever	Actuating rod
	lever	5	lever, adjustable roller lever and actuating rod			
	0 4.7 9.6 11-12 NC 21-22 NC 4.7 2w = 7.1 mm	LS-02/L				
	0 6.5 9.6 13-14 21-22 NO 21-22 4.7 2w = 7.1 mm	LS-11/L	0° 46° 65° 13-14 21-22 NC Zw = 48°	LS-11/RL	LS-11/RLA	
	0 4.7 9.6 15-16 NC 27-28 NO 3.3 2w = 7.7 mm	LS-11D/L				
LS-11S/S	0 47 9.5 21-22 13-14 21-22 13-14 2.6 2w = 7.1 mm	LS-115/L	0' 32' 65' 21-22 13-14 21-22 13-14 21-22 13-14 21-22 13-14 17' 2w = 48'	LS-11S/RL	LS-11S/RLA	LS-11S/RR
	0 4.7 9.6 11-12 NC 21-22 NC 2w = 7.1 mm	LSM-02/L				
	0 6.5 9.6 13-14 21-22 NO 21-22 A.7 2w = 7.1 mm	LSM-11/L	0' 46' 65' 13-14 21-22 NO Zw = 48'	LSM-11/RL	LSM-11/RLA	
	0 4.7 9.6 15-16 NC 27-28 NO 3.3 2w = 7.7 mm	LSM-11D/L				
LSM-11S/S	0 4.7 9.6 21-22 13-14 21-22 13-14 2.6 2w = 7.1 mm	LSM-11S/L	0' 32' 65' 21:22 13:14 21:22 13:14 17 Zw = 48'	LSM-11S/RL	LSM-11S/RLA	LSM-11S/RR



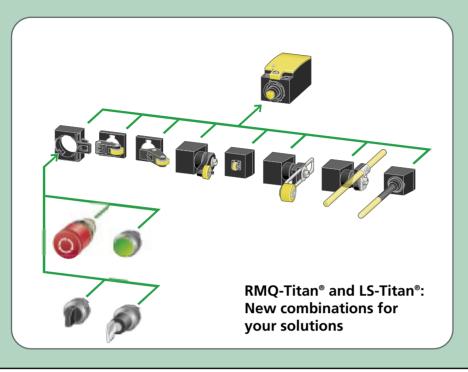
Simply snap on the RMQ-Titan command device

A further unique feature is the ability to combine a control circuit device from the RMQ-Titan range with the LS-Titan position switches. Pushbutton actuators, selector switches or emergency-stop buttons can be simply snapped on directly as the operating heads on each position switch. The combined unit maintains the degree of protection IP66 on both the front and rear.



LSE-Titan® Position Switch U _e =12-30V DC I _e =15-19mA	Contact sequence diagram for plunger	Optical status display, safety category 3 EN 954-1
+Ue	0 0.5 5.5 6.1 Q1 default=3.0	LSE-02
+U _e - electron Q1 Q2	0 0.5 5.5 6.1 Q2 default=3.0	LSE-11

LS-Titan® operating heads, accessories	Roller lever	Angled roller lever	Roller plunger
Plastic version			
	LS-XL	LS-XLA	LS-XP
Metal version	8		
	LSM-XL	LSM-XLA	LSM-XP





The operating head can be attached in all four directions (4 x 90°) and can be installed quickly and securely with a bayonet fitting.

Rotary lever	Adjustable roller lever d=18mm	Adjustable- roller lever d=30mm	Adjustable roller lever d=40mm	Adjustable roller lever d=40mm (Rubber)	Plastic actuating rod	Metal actuating rod	Spring rod actuator	RMQ-Titan fixing adapter
I S VDI	IS VELA	I S YPI A 20	IS VPI AAA	IS VELAMOR	IS YDD	I S YDDM	IE VE	M22.15
LS-XRL	LS-XRLA	LS-XRLA30	LS-XRLA40	LS-XRLA40R	LS-XRR	LS-XRRM	LS-XS	M22-LS
LSM-XRL	LSM-XRLA				LSM-XRR	LSM-XRRM	LSM-XS	
LJW AIL	LJIN AILLA				ZJIII AIIII	LJW ARRIVI	LJIII AJ	

Technical data

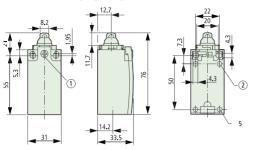
LS-Titan position switches®

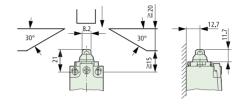
					LS, LSM	LSE
General						
Standards			-		IEC/EN 60947	IEC/EN 61947, EN 954 Level 3, EN61000-4
Climatic proofing						according to IEC 60068-2-3 according to IEC 60068-2-30
Ambient tempera	ture	٥		С	-25/70	-25/70
Mounting position	n				As required	As required
Protection type					IP66	IP66
Terminal capacity		Solid m		m ²	$1 \times (0.5 - 2.5)$	1 × (0.5 – 2.5)
		Flexible with ferrule	· 	mm ²	1 × (0.5 – 1.5)	1 × (0.5 – 1.5)
Supply voltage				VDC		12 20
Rated voltage ¹⁾		42.)/	U_{e}	V DC	_	12 – 30
Rated operationa	current	12 V A			_	0.015
		24 V A	· 		_	0.018
Contacts/switch	ing capacity					0,013
Rated impulse wi			U _{imp}	V AC	4000	_
Rated insulation v			Ui	V	400	_
	gory/pollution degree				III/3	III/3
Rated operational		24 V	$I_{ m e}$	Α	6	_
current	710 13	230 V/240 V	$I_{ m e}$	A	6	_
		400 V/415 V	$\frac{I_{\rm e}}{I_{\rm e}}$	A	4	
	DC-13	24 V	$\frac{I_{\mathrm{e}}}{I_{\mathrm{e}}}$	A	10	0,2
	DC-13	110 V	$\frac{I_{\mathrm{e}}}{I_{\mathrm{e}}}$	A	1	- U.Z
		220 V		A	0.5	
Supply frequency		220 V	I_{e}	Hz	max. 400	
, ,	g in the closed state (IEC/EN 60947-5-1)		ПZ	IIIdX, 400	_
Maximum fus			. ———	A gG/gL	10	_
	g to IEC/EN 60947-5-1	Maximum fuse		A gG/gL	6	partly short-circuit-pro restart after Reset
Repetition accura	cy of switching point			mm	± 0.02	± 0.02
Mechanical vari	ables					
Lifespan		Standard-action contact	Operations	\times 10 ⁶	6	-
		Snap-action contact	Operations	× 10 ⁶	6	3 (electronic)
Contact temperat	ure of roller head			°C	≦ 100	≦ 100
Shock resistance ((half-sinusoidal shock	Standard-action contact		g	30	-
		Snap-action contact	g		30	30
11 ms) to IEC 600	168-2-27	Shap action contact			= 0000	
		Shap detion contact	Operations/h		≦ 6000	≦ 6000
11 ms) to IEC 600		Shap action contact	Operations/h		<u>≥</u> 6000	0.5 – 5.5 mm, freely
11 ms) to IEC 600 Operating frequer Switching point		- Shap dealon connect	Operations/h		<u>≥</u> 60000	0.5 – 5.5 mm, freely adjustable
11 ms) to IEC 600 Operating frequer Switching point Hysteresis	ncy	Just dettor condet	Operations/h		-	0.5 – 5.5 mm, freely adjustable 0.5 mm
11 ms) to IEC 600 Operating frequer Switching point	ncy	Just dettor contact	Operations/h		= 6000 - - -	0.5 – 5.5 mm, freely adjustable
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at		Operations/h N		-	0.5 – 5.5 mm, freely adjustable 0.5 mm
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of				-	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at	Basic units			1.0/8.0	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of	Basic units LS(M)-XP			- - - 1.0/8.0 1,0/8.0	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA		N	1.0/8.0 1.0/8.0 1.0/8.0	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives	N	N N	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 1.0/8.0
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	actuating force at beginning/end of stroke Actuating torque of	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation	N	N N Nm	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke Actuating torque of Max. operating	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation	N	N N Nm m/s	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke Actuating torque of Max. operating	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRLA for angle of actua-	N $\frac{\alpha = 0^{\circ}/30^{\circ}}{\alpha = 0^{\circ}}$	N N Nm m/s	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke Actuating torque of Max. operating	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRLA for angle of actuation	$\frac{N}{\alpha = 0^{\circ}/30^{\circ}}$ $\frac{\alpha = 0^{\circ}}{\alpha = 0^{\circ}}$ $\frac{\alpha = 30^{\circ}, L = 125 \text{ mm}}{\alpha = 30^{\circ}}$	N N Nm m/s m/s	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5
11 ms) to IEC 600 Operating frequent Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke Actuating torque of Max. operating	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation tion LS(M)-XRLA for angle of actuation LS(M)-XRLA for angle of actuation	$\frac{N}{\alpha = 0^{\circ}/30^{\circ}}$ $\frac{\alpha = 0^{\circ}}{\alpha = 30^{\circ}, L = 125 \text{ mm}}$ $L = 130 \text{ mm}$	N N Nm m/s m/s m/s	- 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5
11 ms) to IEC 600 Operating frequent Switching point Hysteresis Switch path resol Actuation	ution Actuating force at beginning/end of stroke Actuating torque of Max. operating	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XRLA for angle of actuation	$\frac{N}{\alpha = 0^{\circ}/30^{\circ}}$ $\frac{\alpha = 0^{\circ}}{\alpha = 30^{\circ}, L = 125 \text{ mm}}$ $\frac{L = 130 \text{ mm}}{\alpha = 30^{\circ}/45^{\circ}}$	N N Nm m/s m/s m/s m/s m/s	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5
11 ms) to IEC 600 Deprating frequer Switching point Hysteresis Switch path resol Actuation Mechanical	actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XR for LS(M)-XLA for angle of actuation LS(M)-XLA for angle of actuation LS(M)-XLA for angle of actuation LS(M)-XP for angle of actuation LS(M)-XP for angle of actuation	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N Nm m/s m/s m/s m/s m/s m/s m/s m/s m/s m/		0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1/1
11 ms) to IEC 600 Deprating frequer Switching point Hysteresis Switch path resol Actuation Mechanical Electromagnetic Electrostatic disch	Actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XRR for LS(M)-XL for angle of actuation LS(M)-XL for angle of actuation LS(M)-XP for angle of actuation CS(M)-XP for angle of actuation LS(M)-XP for angle of actuation CS(M)-XP for angle of actuation	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N N Nm m/s kV		0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1/1
11 ms) to IEC 600 Operating frequer Switching point Hysteresis Switch path resol Actuation Mechanical Electromagnetic Electrostatic disch	Actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam E compatibility (EMO large 2, Level 3, ESD)	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRLA for angle of actuation LS(M)-XRR for LS(M)-XRR for LS(M)-XL for angle of actuation LS(M)-XL for angle of actuation LS(M)-XP for angle of actuation CS(M)-XP for angle of actuation CS(M)-XP for angle of actuation CC) Air discharge Contact discharge	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N N N N Mm m/s m/s m/s m/s m/s m/s m/s m/s m/s kV kV kV		0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1/1
11 ms) to IEC 600 Deprating frequer Switching point Hysteresis Switch path resol Actuation Mechanical Electromagnetic (IEC/EN 61000-4- Electromagnetic f	Actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRR for LS(M)-XRR for LS(M)-XR for angle of actuation LS(M)-XL for angle of actuation LS(M)-XP for angle of actuation CS(M)-XP for angle of actuation LS(M)-XP for angle of actuation CC) Air discharge Contact discharge 1-3, RFI)	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N N N N N M M M M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M M	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1 1/1 8 4 10
11 ms) to IEC 600 Deprating frequents witching point Hysteresis Switch path resol Actuation Mechanical Electromagnetic Electrostatic dische (IEC/EN 61000-4- Electromagnetic from the sure of the sur	Actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam speed with DIN cam arge 2, Level 3, ESD) ields (IEC/EN 61000-4	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRR for angle of actuation LS(M)-XRR for LS(M)-XL for angle of actuation LS(M)-XL for angle of actuation LS(M)-XD for angle of actuation C) Air discharge Contact discharge 1-3, RFI) Supply cables	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N N N N N M M M M S M M	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1/1 8 4 10 2
11 ms) to IEC 600 Deprating frequer Switching point Hysteresis Switch path resol Actuation Mechanical Electromagnetic Electromagnetic fectromagnetic fectromagnetic furst pulses UEC/EN 61000-4-	Actuating force at beginning/end of stroke Actuating torque of Max. operating speed with DIN cam speed with DIN cam arge 2, Level 3, ESD) ields (IEC/EN 61000-4	Basic units LS(M)-XP LS(M)-XL LS(M)-XLA rotary drives Basic units for angle of actuation LS(M)-XRL for angle of actuation LS(M)-XRR for angle of actuation LS(M)-XRR for LS(M)-XL for angle of actuation LS(M)-XL for angle of actuation LS(M)-XD for angle of actuation CS(M)-XP for angle of actuation LS(M)-XR for LS(M)	$\alpha = 0^{\circ}/30^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 0^{\circ}$ $\alpha = 30^{\circ}$, L = 125 mm $\alpha = 30^{\circ}/45^{\circ}$ $\alpha = 30^{\circ}/45^{\circ}$	N N N N N M M M M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M S M M	1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.5	0.5 – 5.5 mm, freely adjustable 0.5 mm 0.04 mm 3.5/8.0 1.0/8.0 1.0/8.0 0.2 1/0.5 1.5 1.5 1.1 1 1 1 1/1 8 4 10

Dimensions

LS-Titan® position switches

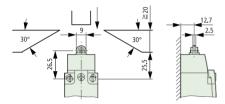
Position switches
LS-..., LSM-..., LSE-...① Tightening torque of cover screw: 1.0 Nm ±02 Nm



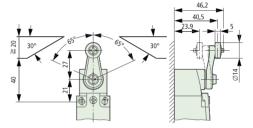


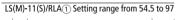
② Only with LS (plastic design)

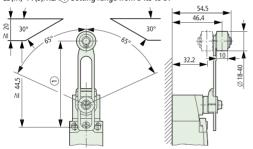
LS-11(S)/P



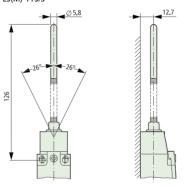




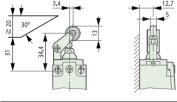




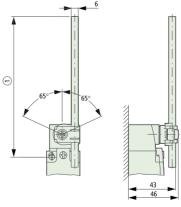
LS(M)-11S/S



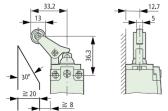




LS(M)-11S/RR①LS.../RR≦ 150

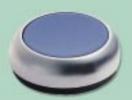






LS.../RRM≦ 210

The New RMQ-Titan® Control Circuit Devices are in Great Shape





LED – lighting of the future for RMQ-Titan[®] control circuit devices





Complete units are available ready for use in standard solutions.

Modern styling has been combined with an optimum range of functions, - ideal for use at machines and on panels. The ergonomically shaped button elements are matched to the shape of a fingertip for even more comfortable operation.

LEDs - the reliable, cost-efficient lighting elements

RMQ-Titan control circuit devices emit light non-stop for over 100 000 hours. The LED elements in RMQ-Titan do not then suddenly fail, however, the strength of their light is simply reduced. Special lenses and coloured LEDs offer enduring reliability at a very attractive price.

Emergency-Stop actuators are now illuminated as well. This safety component is thus clearly visible even in dark rooms and a separate indicator light is not required.

Customized symbols and texts thanks to laser technology

All button plates, indicator lights and legend plates from the RMQ-Titan range of control circuit devices can be inscribed with the required texts and symbols using a laser. The information is burned in and, unlike printed elements, remains there permanently.

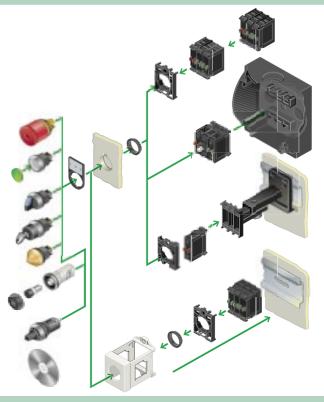
High degrees of protection ensure safety

All RMQ-Titan front elements, apart from the acoustic indicator, have at least degree of protection IP 66.

The applications are already practically limitless, but push-button actuators and indicator lights even have degree of protection IP 69K! They withstand cleaning with a highpressure, or steam-jet device, - essential, for example, for fitting to the outside of refuse collection vehicles.



The new surface mounting enclosures with stainless steel screws and degree of protection IP 66 permit operation of up to six control circuit devices in the harshest of conditions. Optimally suited for use on site.



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