| Niotor Assembly Data for | r: DC040B-2 | (3.90 V/krpi | n) |
|------------------------------|---|-----------------|------------------------|
| Voltage Constant | V | 0.0372 | V/rad/s |
| Voltage Constant | K _E | 3.9 | V/krpm |
| Torque Constant | Κ _T | 0.0372 | Nm/A |
| | | 5.27 | oz-in/A |
| Rated Voltage | V _r | 24 | VDC |
| Rated Torque ^{1,3} | ited Torque ^{1,3} T _r | 0.94 | Nm |
| | 'r | 133.5 | oz-in |
| Rated Speed ^{1,3} | ω _r | 82 | rpm |
| Rated Current ^{1,3} | l _r | 0.90 | А |
| Rated Power ^{1,3} | P _r | 8 | W |
| No-Load Speed ² | ω _{nl} | 89 | rpm |
| No-Load Current ² | l _{nl} | 0.20 | А |
| Resistance (L-L) | R _{mt} | 3.94 | Ohms |
| Inductance (L-L) | L | 3.29 | mH |
| Rotor Inertia | J _r | 0.000032 | kg-m ² |
| | Jr | 0.00046 | oz-in-sec ² |
| Max Winding Temp | θ_{max} | 155 | °C |
| Hall Sensor Spacing | | TBD (60 or 120) | °Elec |
| Poles | | 2 | |
| Winding Configuration | | N/A | |
| Direction of Rotation | | Elec. Rev. | lead end |
| Weight | W _m | 440 | g |
| weight | ••• | 16 | OZ |

Motor Assembly Data for: DC040B-2 (3.90 V/krpm)

Gearbox Data for: G51A (65.5:1)

| Rated Torque | 1.2 | Nm |
|--------------|------|-------|
| | 175 | oz-in |
| Gear Ratio | 65.5 | |
| Efficiency | 0.66 | |

Encoder Data for: None

| Rated Voltage | N/A | VDC |
|-----------------|-----|-----|
| Resolution | N/A | CPR |
| Output Channels | N/A | |
| Output Type | N/A | |

Brake Data for: None

| Rated Voltage | N/A | VDC |
|---------------|-----|-------|
| Rated Torque | N/A | Nm |
| | N/A | oz-in |

¹ Recorded at maximum winding temperature at 25 deg C ambient and without heat sink.

- ² Recorded at Rated Voltage.
- ³ Based on thermal limitations of motor only. See Maximum Speed and Gearbox Rated Torque if applicable for possible additional limitations.

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