

Servo drive CMMT-AS-C2-11A-P3-MP-S1

Part number: 8143165

FESTO



Data sheet

Feature	Value
Type of mounting	Mounting plate, screwed on
Mounting position	Free convection Vertical
Product weight	2100 g
Display	LED green/yellow/red
Control elements	Optional: CDSB operating unit
Conforms to standard	EN 61800-3 EN 61800-5-1 EN 61800-5-2 EN ISO 13849-1
Based on norm	EN 50581 EN 60204-1 EN 61508-1 EN 61508-2 EN 61508-3 EN 61508-4 EN 61508-5 EN 61508-6 EN 61508-7 EN 61800-2 EN 62061
Certification	RCM compliance mark German Technical Control Board (TÜV) c UL us - Listed (OL)
KC characters	KC EMC
CE marking (see declaration of conformity)	As per EU EMC directive as per EU machinery directive As per EU RoHS directive
UKCA marking (see declaration of conformity)	To UK instructions for EMC To UK instructions for machines To UK RoHS instructions
Certificate issuing authority	German Technical Control Board (TÜV) Rheinland 01/205/5640.00/18 TÜV Rheinland UK Ltd. 01/205U/5640.00/22 UL E331130
Storage temperature	-25 °C ... 55 °C
Ambient temperature	0 °C ... 50 °C
Note on ambient temperature	Above an ambient temperature of 40 °C, the power must be reduced by 3%/°C.
UL-ambient temperature	0 °C ... 40 °C
Relative air humidity	5 - 90 % Non-condensing
Max. installation height	2000 m

Feature	Value
Information on max. installation height	1% power reduction/100 m above 1000 m.
Degree of protection	IP20
Protection class	I
Overvoltage category	III
Contamination level	2
Surge resistance	6 kV
Note on materials	RoHS-compliant
LABS (PWIS) conformity	VDMA24364 zone III
Nominal operating voltage phases	3-phase
Nominal operating voltage AC	400 V
Permissible voltage fluctuations	+/- 10 %
Input voltage range AC	200 V ... 480 V
Mains frequency	48 Hz ... 62 Hz
Nominal current load supply	2 A
Peak current, load supply	6 A
Active PFC	no
Line filter	Integrated
System voltage to EN 61800-5-1	300 V
Max. short circuit protection of mains	10 kA
Mains types	TN IT
Nominal voltage, load supply DC	560 V
Load supply permissible range	± 10 %
Max. DC link voltage	800 V
Braking resistor, integrated	130 Ohm
Pulse power of braking resistor	5 kVA
Pulse energy for braking resistor	850 Ws
Braking resistor nominal power (IEC)	48 W
Braking resistor, external	130 Ohm ... 250 Ohm
Max. continuous output of the external braking resistor (IEC)	400 W
Nominal voltage, logic supply DC	24 V
Permissible range of logic voltage	± 20 %
Max. current consumption for logic supply without clamping brake	0.5 A
Max. current consumption for logic supply with parking brake	1.5 A
Max. current consumption for logic supply with clamping brake and I/O	2 A
Output voltage range AC	3x (0 – input) V
Nominal current per phase, effective	1.7 A
Peak current per phase, effective	5.1 A
Max. peak current duration	2 s
Controller nominal power	800 VA
Peak power	2400 VA
Output frequency	0 Hz ... 599 Hz
Max. length of motor cable without ext. mains filter	50 m
Max. output current of holding brake	1 A
Max. voltage drop from logic supply to brake output	0.8 V
Number of inputs for motor temperature sensor	1
Controller operating mode	Cascade control P position controller PI speed controller PI current regulator for F or M Profile operation with block mode and direct mode Interpolating mode via fieldbus Synchronous operating modes Reference travel Setup mode Autotuning

Feature	Value
Mode of operation	Field-oriented regulation Position resolution 24 bit/rev. Sampling rate 16 kHz PWM with 8 or 16 KHz Vector modulation with 3rd harmonic Real-time data acquisition 2x input capture (x, v, F) 2x output trigger (x, v, F) 2x position sensor input 1x SYNC interface for encoder emulation or encoder input
Ethernet interface, function	Parameterization and commissioning
Ethernet interface, protocol	TCP/IP
Fieldbus interface, protocol	EtherCAT EtherNet/IP Modbus®/TCP PROFINET IRT PROFINET RT
Fieldbus interface, function	Bus connection, incoming/forwarding EtherCAT® slave PROFINET slave EtherNet/IP slave
Fieldbus coupling	EtherCAT EtherNet/IP Modbus®/TCP PROFINET
Communication profile	CiA402 CoE (CANopen over EtherCAT) EoE (Ethernet over EtherCAT) FoE (File over EtherCAT) PROFdrive DriveProfile
Process interfacing	AC1: Adjustable-Speed Drives AC3: drives with positioning function AC4: Synchronous Servo Application Adjustable-Speed Drives Drives with positioning function I/O mode for 256 positioning blocks Interpolated mode CSP Interpolated mode CST Interpolated mode CSV
Fieldbus interface, transmission rate	100 Mbit/s
Fieldbus interface, connection type	2x socket
Fieldbus interface, connection technology	RJ45
Encoder interface, function	BiSS-C EnDat® 2.1 encoder EnDat® 2.2 encoder Hiperface encoder Incremental encoder Nikon SIN/COS encoder
Encoder interface 2, function	Incremental encoder SIN/COS encoder
Synchronization interface, function	Encoder emulation A/B/Z Encoder input A/B/Z
Encoder interface output, characteristics	1 MHz maximum output frequency max. 16384 ppr
Encoder interface input, characteristics	1 MHz maximum output frequency max. 16384 ppr
Number of digital logic inputs	12
Input switching logic	PNP (positive switching)
Characteristics of logic input	Freely configurable in some cases Safety inputs in some cases Not galvanically isolated
Logic input specification	Based on IEC 61131-2, type 3
Work range of logic input	-3 V ... 30 V

Feature	Value
Number of high-speed logic inputs	2
Time resolution of high-speed logic inputs	1 μ s
Number of digital logic outputs 24 V DC	6
Switching logic at outputs	PNP (positive switching)
Characteristics of digital logic outputs	Freely configurable in some cases Not galvanically isolated Diagnostic outputs in some cases
Max. current of digital logic outputs	20 mA
Number of high-speed switching outputs	2
Time resolution of high-speed switching outputs	1 μ s
Number of floating switching outputs	1
Max. current of the floating switching outputs	50 mA
Number of analog setpoint inputs	1
Characteristics of setpoint inputs	Differential inputs Configurable for rotational speed Configurable for current/force
Work range of setpoint input	± 10 V
Operating range of analog inputs	± 10 V
Impedance of setpoint input	70 kOhm
Safety function	Safe brake control (SBC) Safe torque off (STO) Safe stop 1 (SS1)
Safety integrity level (SIL)	Safe brake control (SBC)/SIL 3/SILCL 3 Safe torque off (STO)/SIL 3/SILCL 3
Performance Level (PL)	Safe brake control (SBC)/category 3, performance level e Safe torque off (STO)/category 4, performance level e
Diagnostic coverage	97 %
SFF safe failure fraction	99 %
Hardware fault tolerance	1
Number of safe 2-pin inputs	2
Number of diagnostic outputs	2